NDK_GARCHM_FORE

Last Modified on 07/15/2016 9:51 am CDT

- C/C++
- .Net

intstdcall NDK_GARCHM_FORE(dou	uble *	pData,
size	e_t	nSize,
dou	uble *	sigmas,
size	e_t	nSigmaSize,
dou	uble	mu,
dou	uble	flambda,
con	nst double *	Alphas,
size	e_t	p,
con	nst double *	Betas,
size	e_t	q,
WO	RD	nInnovationType,
dou	uble	nu,
size	e_t	nStep,
WO	RD	retType,
dou	uble	alpha,
dou	uble *	retVal
)		

Calculates the out-of-sample forecast statistics.

Returns

status code of the operation

Return values

NDK_SUCCESSOperation successfulNDK_FAILEDOperation unsuccessful. See Macros for full list.

Parameters

[in]	pData	is the univariate time series data (a one dimensional array).
[in]	nSize	is the number of observations in pData.
[in]	sigmas	is the univariate time series data (a one dimensional array of cells (e.g. rows or columns)) of the last q realized volatilities.
[in]	nSigmaSize	is the number of elements in sigmas. Only the latest q observations are used.
[in]	mu	is the GARCH model conditional mean (i.e. mu).
[in]	flambda	is the volatility coefficient for the mean. In finance, lambda is referenced as the risk premium.
[in]	Alphas	are the parameters of the ARCH(p) component model (starting with the lowest lag).

[in] p	is the number of elements in Alphas array
[in] Betas	are the parameters of the GARCH(q) component model (starting with
	the lowest lag).
[in] q	is the number of elements in Betas array
[in] nlnnovationTy	pe is the probability distribution function of the innovations/residuals
	(see INNOVATION_TYPE)
	 INNOVATION_GAUSSIAN Gaussian or Normal Distribution
	 INNOVATION_TDIST Student's T-Distribution,
	 INNOVATION_GED Generalized Error Distribution (GED)
c 1 - 1	
[in] nu	is the shape factor (or degrees of freedom) of the
	innovations/residuals probability distribution function.
[in] nStep	is the forecast time/horizon (expressed in terms of steps beyond end of
	the time series).
[in] retType	is a switch to select the type of value returned
	1. Mean forecast
	2. Forecast Error
	3. Volatility term structure
	4. Confidence interval lower limit
	5. Confidence interval upper limit (see FORECAST_RETVAL_FUNC)
[in] alaba	is the statistical similiar as level if mission, a default of 50/ is
[in] alpha	is the statistical significance level. If missing, a default of 5% is
	assumed.
[out]retVal	is the calculated forecast value

Remarks

- 1. The data sample may include missing values (NaN).
- The test hypothesis for the population standard deviation: \[H_{o}: \sigma =\sigma_o\] \[H_{1}: \sigma \neq \sigma_o\] Where:
 - The underlying model is described here.
 - The time series is homogeneous or equally spaced.
 - The time series may include missing values (e.g. #N/A) at either end.
 - The number of parameters in the input argument alpha determines the order of the ARCH component model.
 - The number of parameters in the input argument beta determines the order of the GARCH component model.

Requirements

Header	SFSDK.H
Library	SFSDK.LIB
DLL	SFSDK.DLL

int NDK_GARCHM_FORE(double[] UIntPtr double[] UIntPtr double double double UIntPtr double[] UIntPtr double[] UIntPtr short double UIntPtr short ref double	pData, nSize, pVols, npVolSize, mu, flambda, Alphas, p, Betas, q, nInnovationType, nu, nStep, retType, e retVal	Namespace: NumXLAPI Class: SFSDK Scope: Public Lifetime: Static
)	e retVal	
Calculates the out-of-sample forecas	st statistics.	

a value from **NDK_RETCODE** enumeration for the status of the call.

NDK_SUCCESS operation successful

Error Error Code

Parameters

[in] pData	is the univariate time series data (a one dimensional array).	
[in] nSize	is the number of observations in pData.	
[in] mu	is the GARCH model conditional mean (i.e. mu).	
[in] flambda	is the volatility coefficient for the mean. In finance, lambda is referenced	
	as the risk premium.	
[in] Alphas	are the parameters of the ARCH(p) component model (starting with the	
	lowest lag).	
[in] p	is the number of elements in Alphas array	
[in] Betas	are the parameters of the GARCH(q) component model (starting with	
	the lowest lag).	
[in] q	is the number of elements in Betas array	
[in] nInnovationType is the probability distribution function of the innovations/residuals		
	(see INNOVATION_TYPE)	
	 INNOVATION_GAUSSIAN Gaussian or Normal Distribution 	
	 INNOVATION_TDIST Student's T-Distribution, 	
	 INNOVATION_GED Generalized Error Distribution (GED) 	
[in] nu	is the shape factor (or degrees of freedom) of the	

	innovations/residuals probability distribution function.
[in] nStep	is the forecast time/horizon (expressed in terms of steps beyond end of
	the time series).
[in] retType	is a switch to select the type of value returned
	1. Mean forecast
	2. Forecast Error
	3. Volatility term structure
	4. Confidence interval lower limit
	Confidence interval upper limit (see FORECAST_RETVAL_FUNC)
[out]retVal	is the calculated forecast value

Remarks

- 1. The data sample may include missing values (NaN).
- The test hypothesis for the population standard deviation: \[H_{o}: \sigma =\sigma_o\] \[H_{1}: \sigma \neq \sigma_o\] Where:
 - The underlying model is described here.
 - The time series is homogeneous or equally spaced.
 - $\circ~$ The time series may include missing values (e.g. #N/A) at either end.
 - The number of parameters in the input argument alpha determines the order of the ARCH component model.
 - The number of parameters in the input argument beta determines the order of the GARCH component model.

Exceptions

Exception Type	Condition
None	N/A

Requirements

Namespace	NumXLAPI
Class	SFSDK
Scope	Public
Lifetime	Static
Package	NumXLAPI.DLL

References

Hamilton, J.D.; Time Series Analysis, Princeton University Press (1994), ISBN 0-691-04289-6 Tsay, Ruey S.; Analysis of Financial Time Series John Wiley & SONS. (2005), ISBN 0-471-690740

See Also

[template("related")]